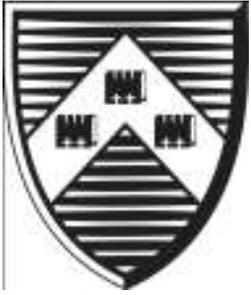


Set-Membership Constrained Widely Linear Beamforming Algorithms

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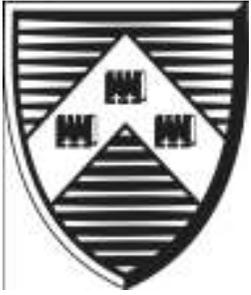
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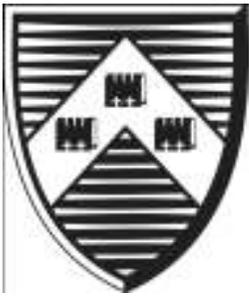
Outline

- Introduction
- System model and problem statement
- Set-membership widely-linear beamforming techniques
- Proposed set-membership filtering widely-linear algorithms
- Simulations
- Conclusions



Introduction

- Modern electronic systems like radar and sonar use antenna arrays and rely on adaptive beamforming techniques, whose design is still a major research problem.
- A great deal of research has been done on linearly constrained minimum variance (LCMV) beamforming that employ the second-order statistics of the data.
- Widely-linear (WL) processing can improve the performance of the LCMV based algorithms when the data are second-order noncircular at the expense of a higher computational cost.
- Set-membership filtering (SMF) techniques can reduce costs by performing data selective updates and can provide extra flexibility in the design.
- We propose the combination of SMF techniques with WL processing for the design of LCMV beamforming and develop LMS and RLS algorithms.



System Model and Problem Statement

- We consider a sensor array processing system equipped with a ULA with M elements and K narrow-band sources in the far field
- The received vector from the linear array can be modelled as

$$x = A(\theta)s + n \in \mathbb{C}^M$$

- The problem:
 - Design of LCMV beamformer

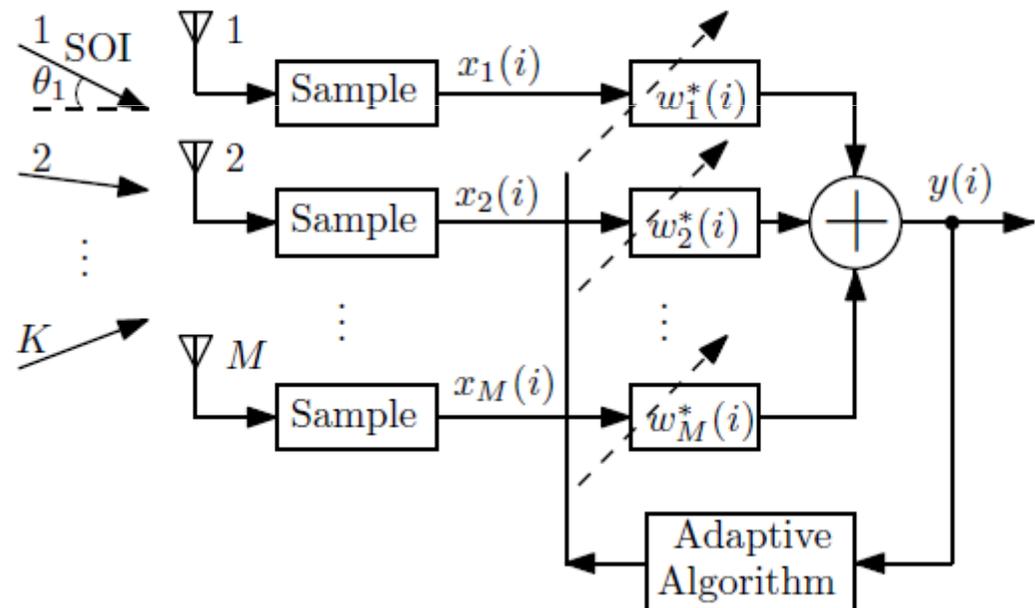
$$\text{minimize } E[|w^H x|^2] = w^H R_x w$$

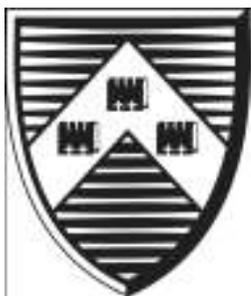
$$\text{subject to } w^H a(\theta_k) = 1$$

- Batch solution

$$w_{\text{opt}} = \frac{R_x^{-1} a(\theta_k)}{a^H(\theta_k) R_x^{-1} a(\theta_k)}$$

- Adaptive algorithms





Set-Membership Widely-Linear Beamforming Techniques

- In the presence of non-circular data, widely-linear processing techniques can improve the performance of adaptive beamforming algorithms.
- This is done by taking into account all the second-order statistics of the received signal \mathbf{x}
- A simple way to do that is to use a transformation that augments \mathbf{x}

$$\mathbf{x} \xrightarrow{\tau} \mathbf{x}_a : \mathbf{x}_a = [\mathbf{x}^T, \mathbf{x}^H]^T \in \mathbb{C}^{2M}$$

- Problem: this doubles the dimension of the data structures and increases the cost.
- We propose a SMF- approach to widely-linear beamforming, which only updates the weights if a bound is satisfied with the following steps:
 - 1) information evaluation and computation of the bound
 - 2) update of the weights if the bound is exceeded.



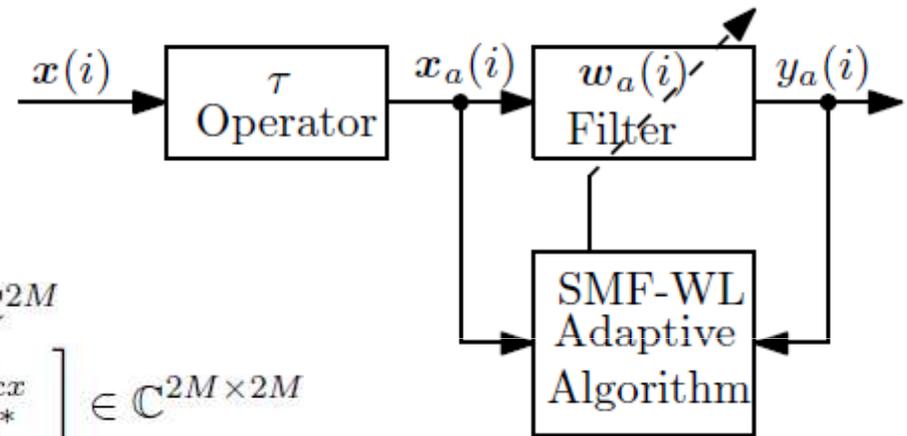
Proposed SMF-WL Algorithms (1/3)

- Widely-linear LCMV optimization:

$$\begin{aligned} \text{minimize } E[|y|^2] &= E[|w_a^H x_a|^2] = w_a^H R_{ax} w_a \\ \text{subject to } w_a^H a_a(\theta_k) &= 1 \end{aligned}$$

where

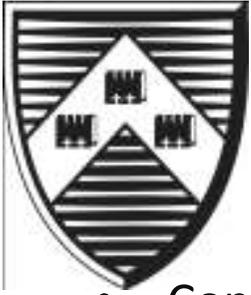
$$\begin{aligned} a_a(\theta_k) &= [a^T(\theta_k), a^H(\theta_k)]^T \in \mathbb{C}^{2M} \\ R_{ax} &= E[x_a(i)x_a^H(i)] = \begin{bmatrix} R_x & R_{cx} \\ R_{cx}^* & R_x^* \end{bmatrix} \in \mathbb{C}^{2M \times 2M} \end{aligned}$$



- Solution:

$$w_{a\text{-opt}} = \frac{R_{ax}^{-1} a_a(\theta_k)}{a_a^H(\theta_k) R_{ax}^{-1} a_a(\theta_k)}$$

- Adaptive algorithms:
 - LMS
 - RLS



Proposed SMF-WL Algorithms (2/3)

- Consider the Lagrangian associated with the optimisation problem:

$$\mathcal{L}(\mathbf{w}_a(i), \lambda_l) = E[|\mathbf{w}_a^H(i)\mathbf{x}_a(i)|^2] + 2\Re[\lambda_l(\bar{\mathbf{w}}_a^H(i)\mathbf{a}_a(\theta_k) - 1)]$$

- The SMF-WL-LMS algorithm is given by:

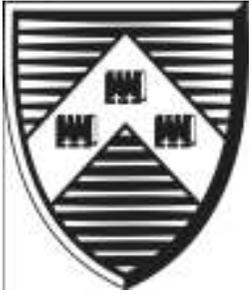
$$\mathbf{w}_a(i+1) = \mathbf{w}_a(i) - \mu y^*(i) \left(\mathbf{I} - \frac{\mathbf{a}_a(\theta_k)\mathbf{a}_a^H(\theta_k)}{\mathbf{a}_a^H(\theta_k)\mathbf{a}_a(\theta_k)} \right) \mathbf{x}_a(i)$$

- A simple and effective time-varying bound is given by

$$\delta(i) = \beta\delta(i-1) + (1-\beta)\sqrt{\alpha\|\mathbf{w}_a\|^2\hat{\sigma}_n^2}$$

- A step size rule that controls the data selective updates is given by

$$\mu(i+1) = \begin{cases} \frac{1 - \frac{\delta(i)}{|y_a(i)|}}{\mathbf{x}_a^H(i) \left(\mathbf{I} - \frac{\mathbf{a}_a(\theta_k)\mathbf{a}_a^H(\theta_k)}{\mathbf{a}_a^H(\theta_k)\mathbf{a}_a(\theta_k)} \right) \mathbf{x}_a(i)} & \text{if } |y|^2 > \delta^2 \\ 0 & \text{if } |y|^2 \leq \delta^2 \end{cases}$$



Proposed SMF-WL Algorithms (3/3)

- Consider the Lagrangian associated with the optimisation problem:

$$\mathcal{L}(w_a(i), \mu_l) = \sum_{j=1}^i \alpha_l^{i-j} |w_a^H(i) x_a(j)|^2 + 2\Re[\lambda_l (w_a^H(i) a_a(\theta_k) - 1)]$$

- The SMF-WL-RLS algorithm is given by:

$$w_a(i) = \frac{\hat{R}_{ax}^{-1}(i) a_a(\theta_k)}{a_a^H(\theta_k) \hat{R}_{ax}^{-1}(i) a_a(\theta_k)}$$

$$R_{ax}^{-1}(i) = \alpha^{-1}(i) R_{ax}^{-1}(i-1) - \alpha^{-1}(i) G(i) x_a^H(i) R_{ax}^{-1}(i-1)$$

$$G(i) = \frac{R_{ax}^{-1}(i) x_a(i)}{\alpha(i) + x_a^H(i) R_{ax}^{-1}(i) x_a(i)}$$

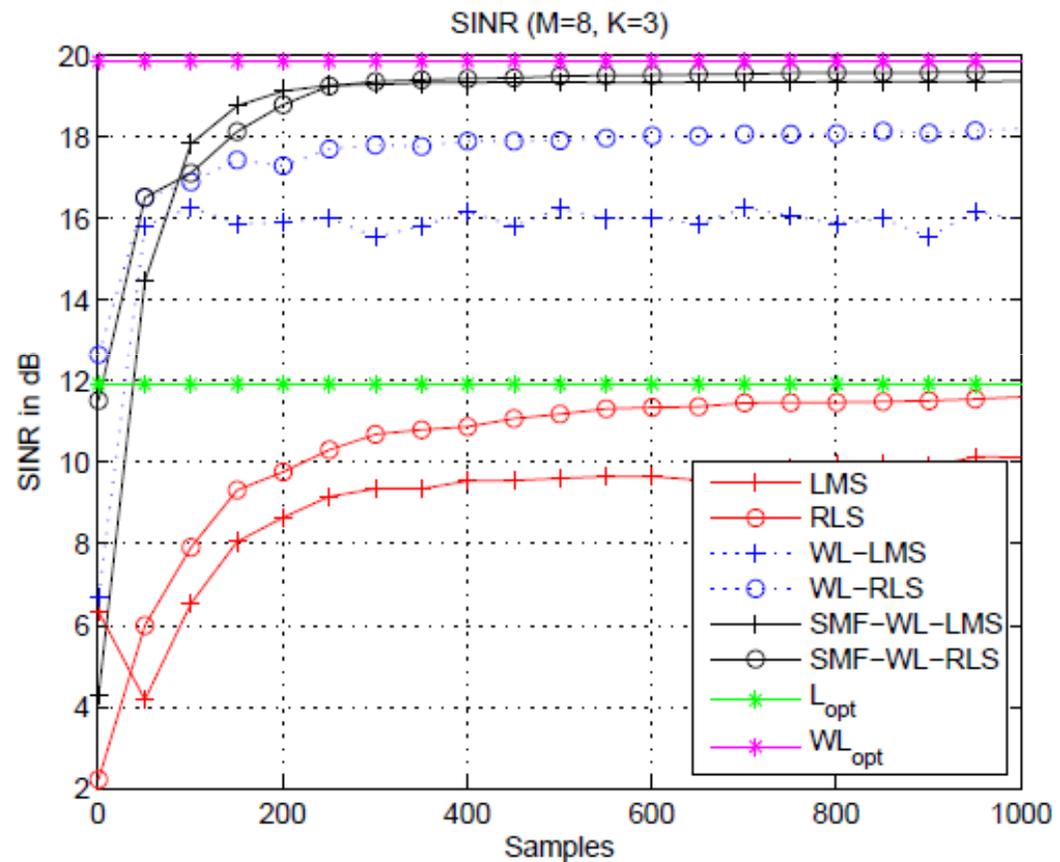
- The variable forgetting factor rule that controls the data selective updates is:

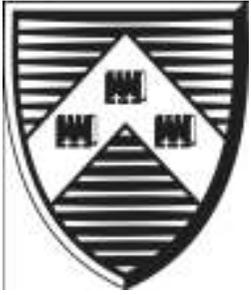
$$\alpha(i) = \begin{cases} \frac{a_a^H(\theta_k) R_{ax}^{-1}(i) [\delta(i) a_a(\theta_k) - x_a(i)]}{a_a^H(\theta_k) G(i) x_a(i) R_{ax}^{-1}(i) [\delta(i) a_a(\theta_k) - x_a(i)]} & \text{if } |y|^2 > \delta^2 \\ 0 & \text{if } |y|^2 \leq \delta^2 \end{cases}$$



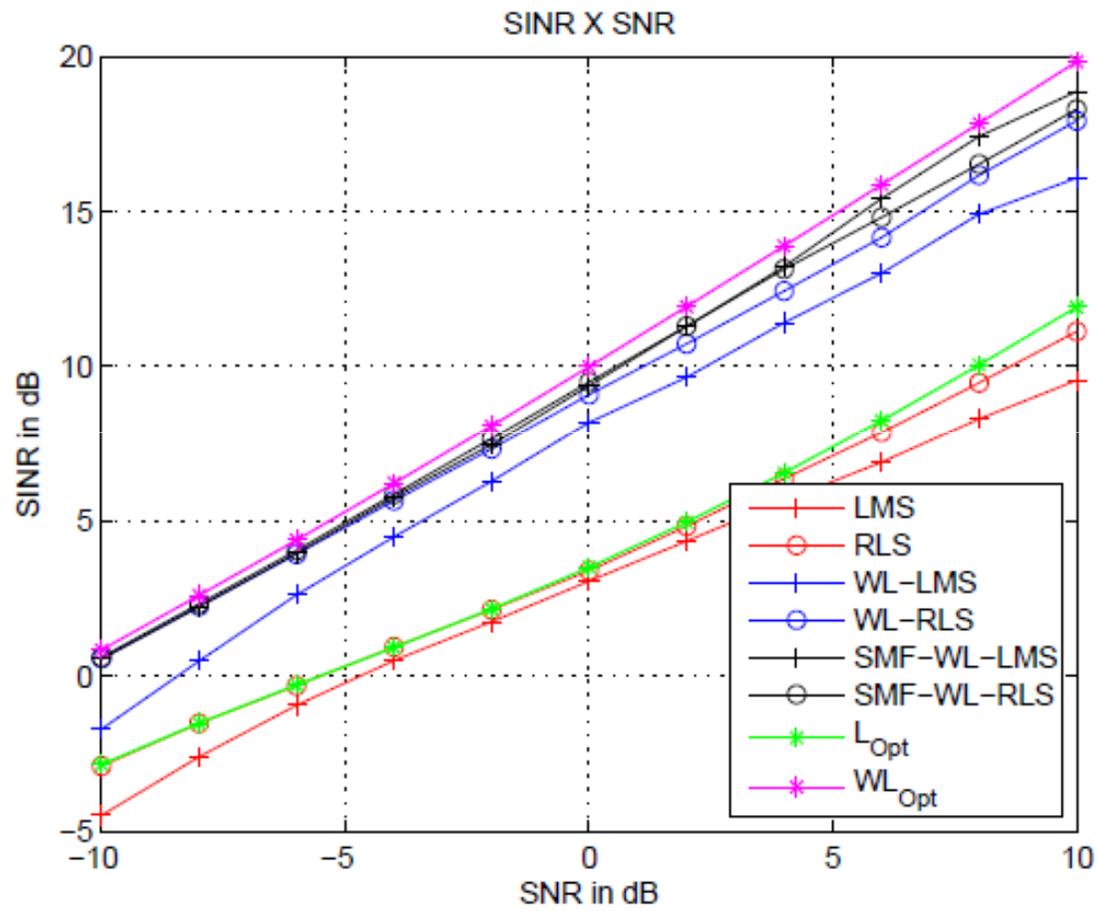
Simulations (1/4)

- We consider a ULA with 8 elements.
- The system has 1 desired user and 2 interferers with the same power with DOAs equal to 20, 50, -30 degrees.
- The noise is modelled as AWGN with zero mean and variance σ^2



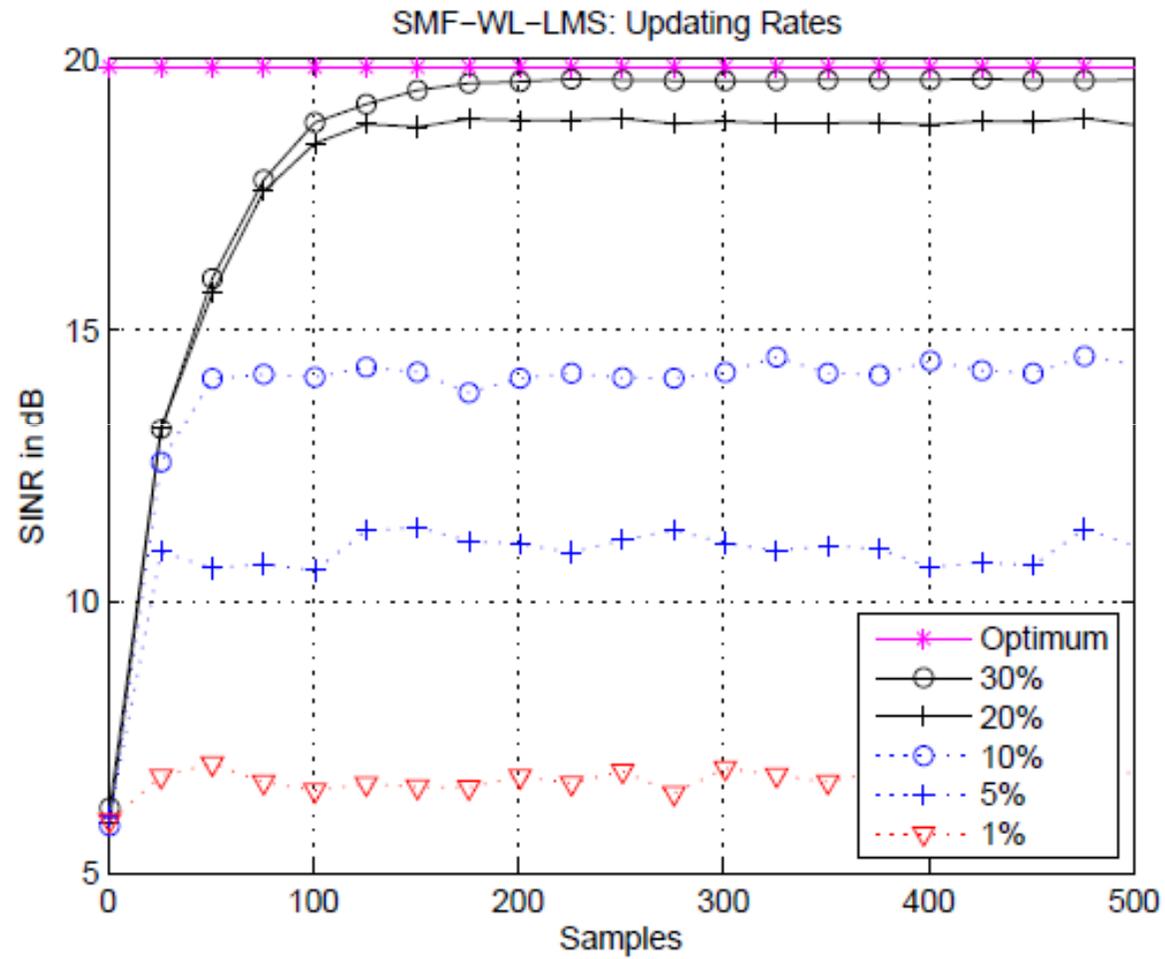


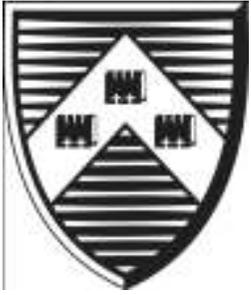
Simulations (2/4)



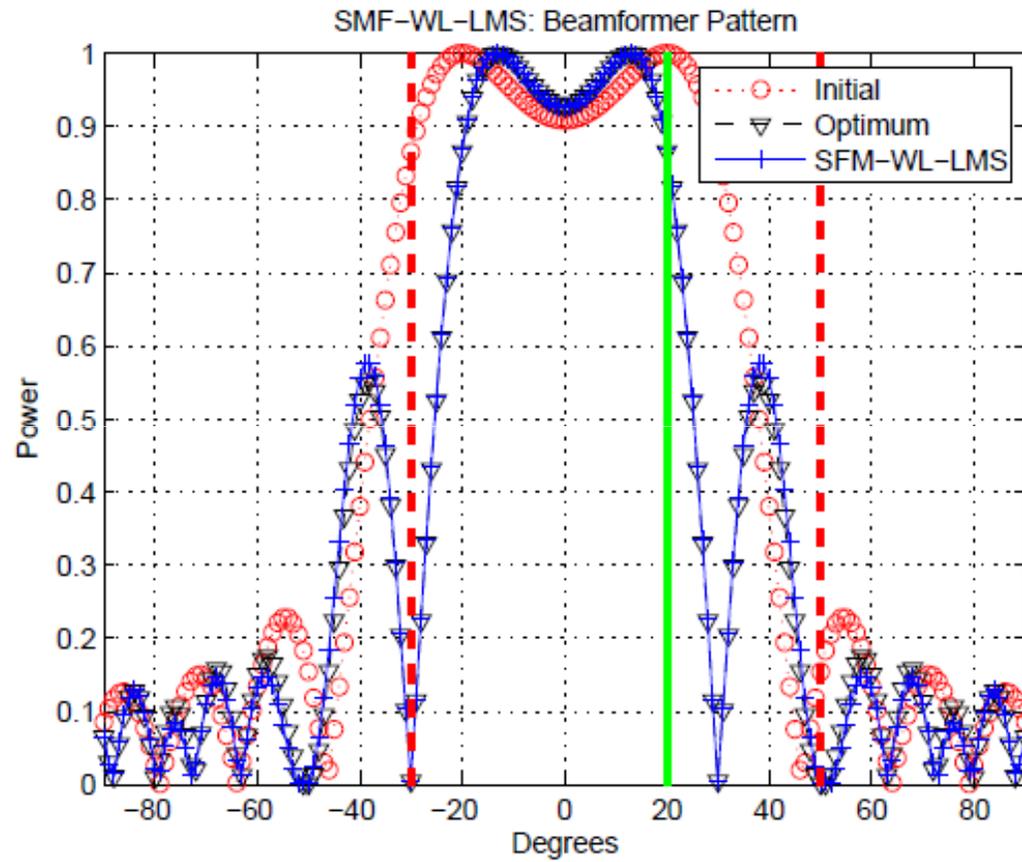


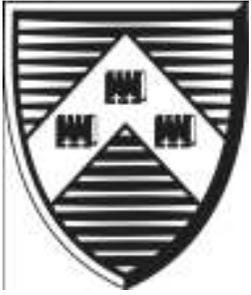
Simulations (3/4)





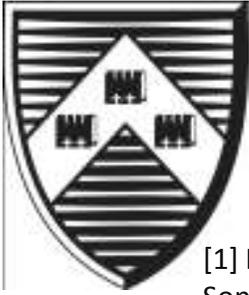
Simulations (4/4)





Conclusions

- We have developed distributed SMF-WL beamforming algorithms for low-complexity adaptive beamforming applications.
- We have devised both LMS and RLS versions that can be used for various applications in sensor arrays.
- The proposed SMF-WL algorithms can exploit non-circular data for an improved performance and have a reduced computational cost.
- Simulation results have shown that the proposed SMF-WL algorithms perform very close to the optimal solutions.



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